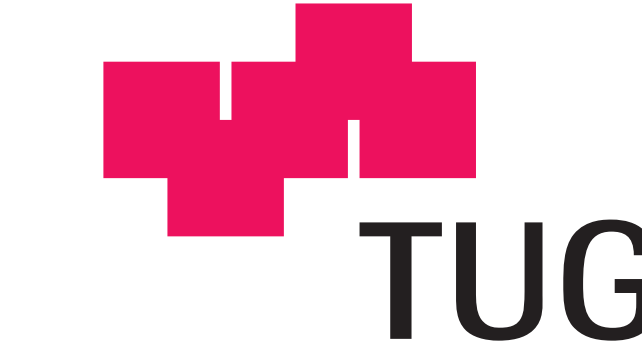
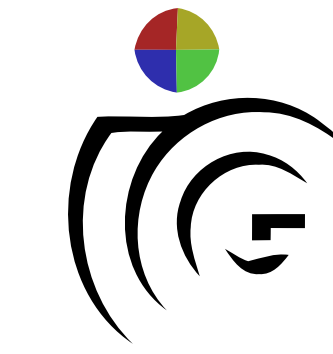


Maximum Persistency via Iterative Relaxed Inference with Graphical Models

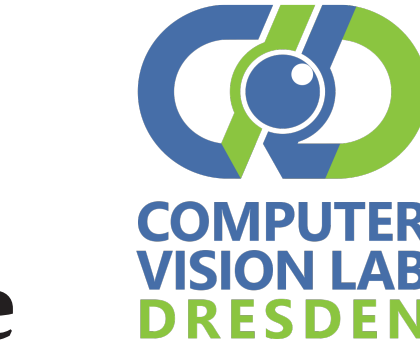
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INTRODUCTION

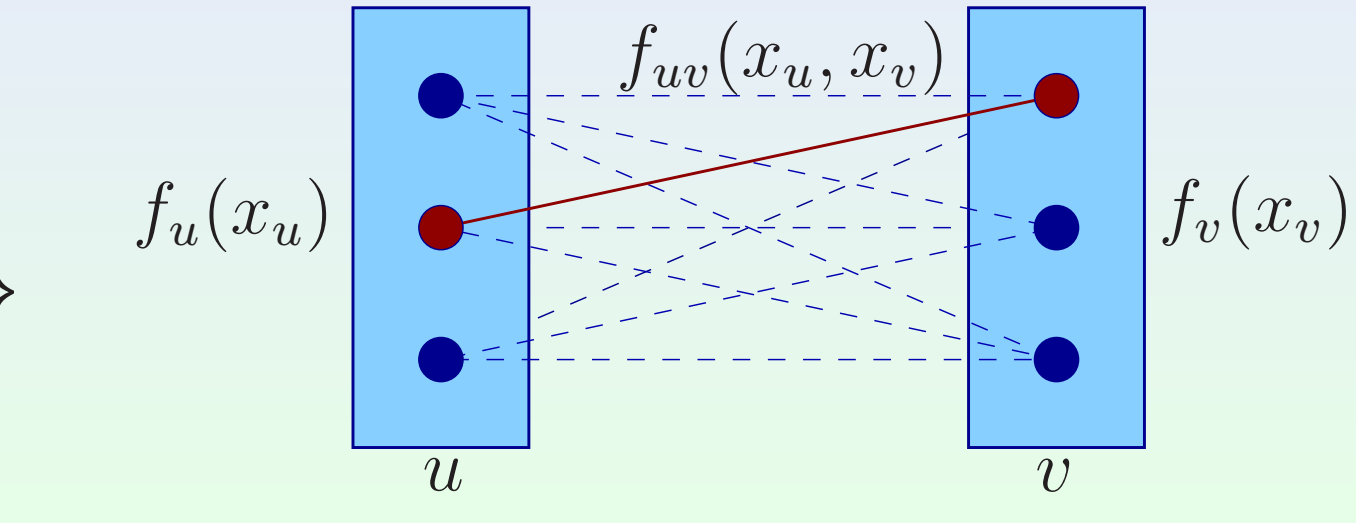
Abstract

- We consider: energy minimization for graphical models
- We obtain: a part of a globally optimal solution (persistent assignment)
- Properties:
 - scalable algorithm
 - maximizes the number of persistent variables
 - provably outperforms most of existing techniques

Energy Minimization

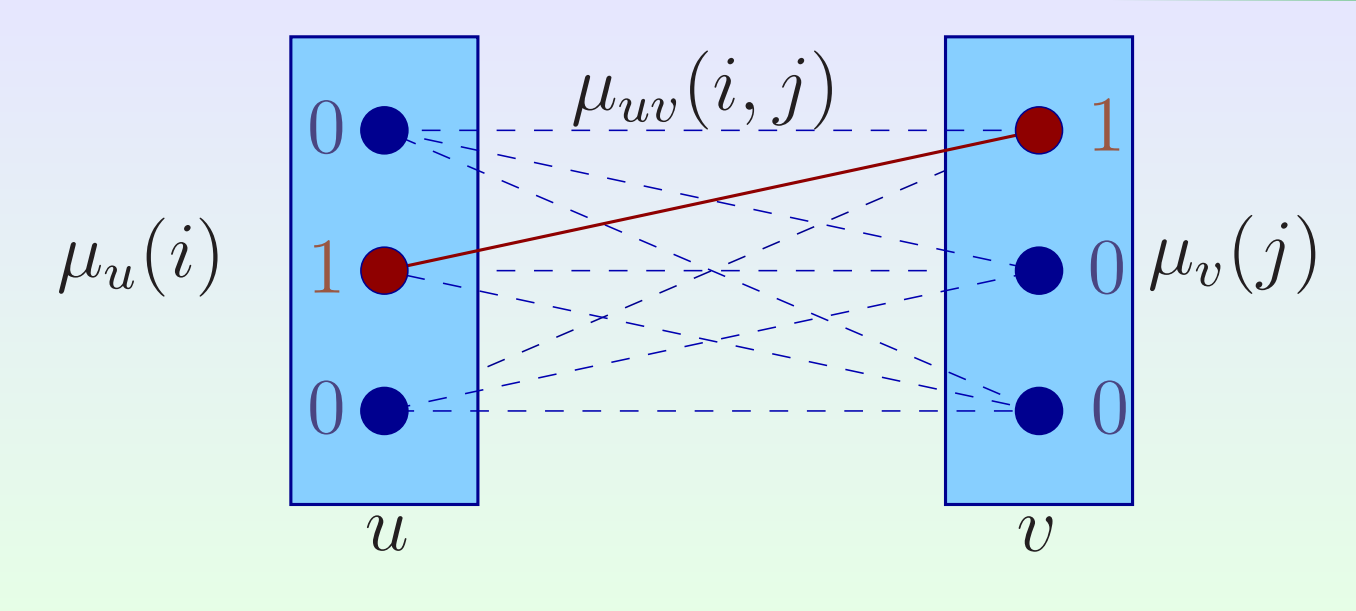
Given a graph $(\mathcal{V}, \mathcal{E})$, associated variables $x_v \in \mathcal{X}_v$, $v \in \mathcal{V}$, and potentials $f_c(x_c) \in \mathbb{R}$, $c \in \mathcal{V} \cup \mathcal{E}$, we consider the energy minimization problem:

$$\begin{aligned} \min_{x \in \mathcal{X}} E_f(x) \\ = \min_{x \in \mathcal{X}} \left\{ \sum_{v \in \mathcal{V}} f_v(x_v) + \sum_{uv \in \mathcal{E}} f_{uv}(x_u, x_v) \right\} \\ = \min_{x \in \mathcal{X}} \langle f, \delta(x) \rangle \end{aligned}$$

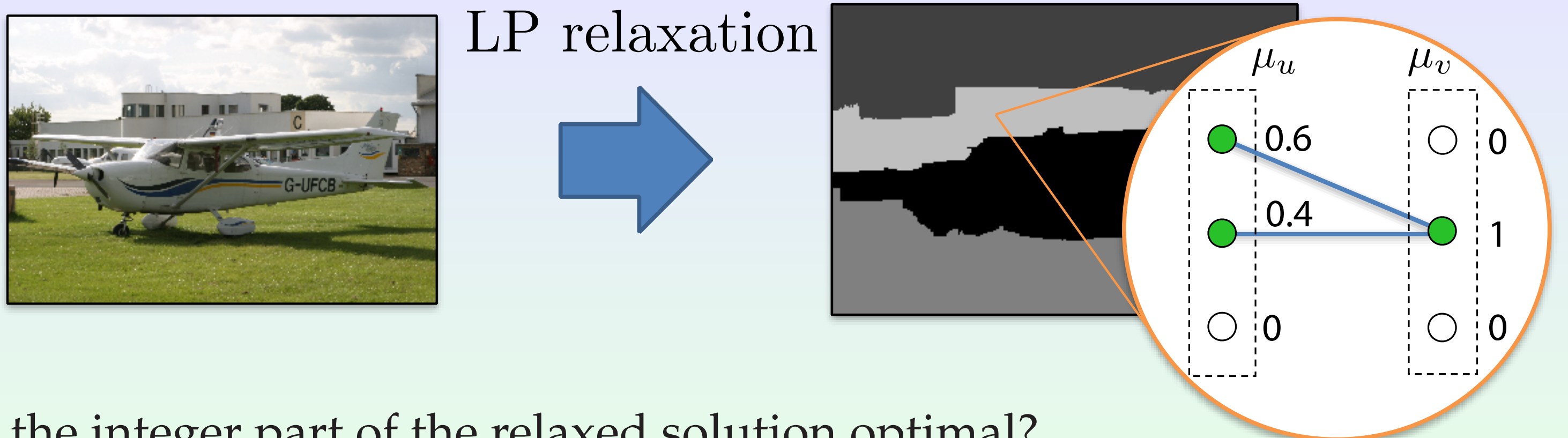


ILP / LP Relaxation

$$\begin{aligned} = \min_{\mu \in \text{conv}(\delta(\mathcal{X}))} \langle f, \mu \rangle \geq \min_{\mu} \langle f, \mu \rangle \\ \Lambda \begin{cases} \sum_i \mu_u(i) = 1 \\ \sum_j \mu_{uv}(i, j) = \mu_u(i) \\ \mu \geq 0 \end{cases} \end{aligned}$$



Persistency



- Is the integer part of the relaxed solution optimal?
- Can we eliminate labels that are not in the support set of relaxed solutions?

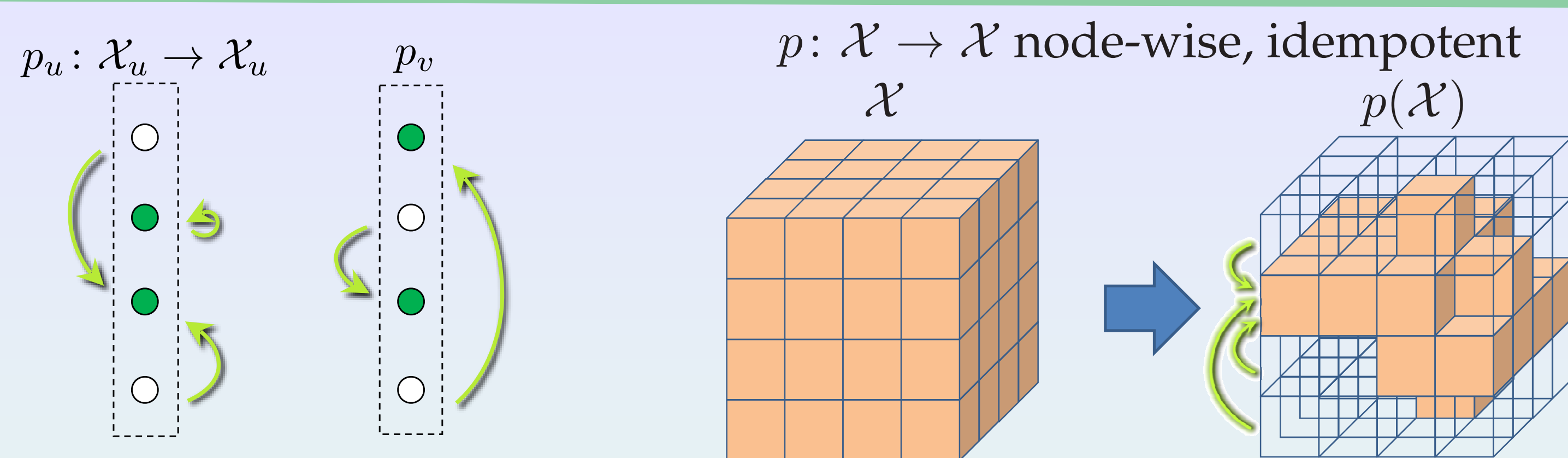
Progress in Partial Optimality Methods

Graph cut - based		LP - based	
Courtesy of Kovtun [11] 93.6% (instance not available)	Instance used by Alahari et al [2] Kovtun's method: 1s, 87.6%	Shekhovtsov [13] LP-windowing: 1.5h, 94%	Our: 22s, 96.7% strong
Kovtun's method: 1s, 0.2%	Kohli et al [8] (MQPBO) 41s, 0.2%	Swoboda et al [17] (PBP optimal) 27min, 89.8%	Our: 16s, 99.94% strong

• Model 1 [11, 2]: Potts, strong unaries; • Model 2 [18]: per-pixel unaries.

RELAXED-IMPROVING MAPPING

Improving Mapping (Substitution of labels)



Definition: Mapping $p: \mathcal{X} \rightarrow \mathcal{X}$ is *improving* if $\forall x E_f(p(x)) \leq E_f(x)$

- Equivalent to: $\min_{x \in \mathcal{X}} (E_f(x) - E_f(p(x))) \geq 0$

The difference energy $E_g(x)$, $g = f - P^T f$
(What is P ?: $(P^T f)_c(x_c) = f_c(p_c(x_c))$, or, in primal: $P\delta(x) = \delta(p(x))$)

Definition: Mapping p is *relaxed-improving* if $\min_{\mu \in \Lambda} \langle (I - P^T)f, \mu \rangle \geq 0$ **(P)**

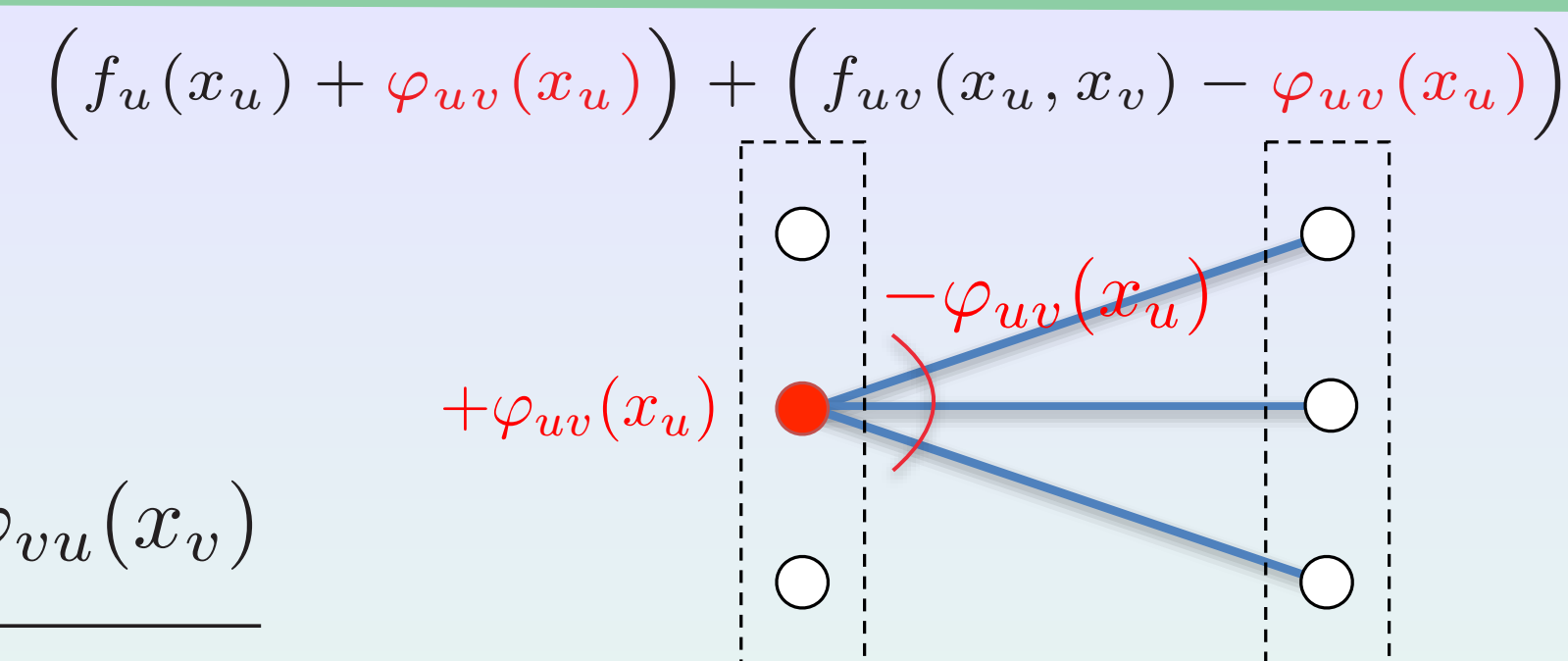
Dually, Through Equivalent Transformations

Equivalent Transformations:

$(\forall x \in \mathcal{X}) E_f(x) = E_{f_\varphi}(x)$

$$f_u^\varphi(x_u) := f_u(x_u) + \sum_{v \in \mathcal{N}(u)} \varphi_{uv}(x_u)$$

$$f_{uv}^\varphi(x_u, x_v) := f_{uv}(x_u, x_v) - \varphi_{uv}(x_u) - \varphi_{vu}(x_v)$$



- Consider locally improving condition: $f_c(p_c(x_c)) \leq f_c(x_c)$, $\forall x_c$

- + equiv. transformations: $\exists \varphi \forall c \in \mathcal{V} \cup \mathcal{E}, \forall x_c f_c^\varphi(p_c(x_c)) \leq f_c^\varphi(x_c)$ **(D)**

Theorem: The primal **(P)** and dual **(D)** definitions are equivalent.

THE PROBLEM

Maximum Persistency

- Given that the verification problem is solvable, which method is better?

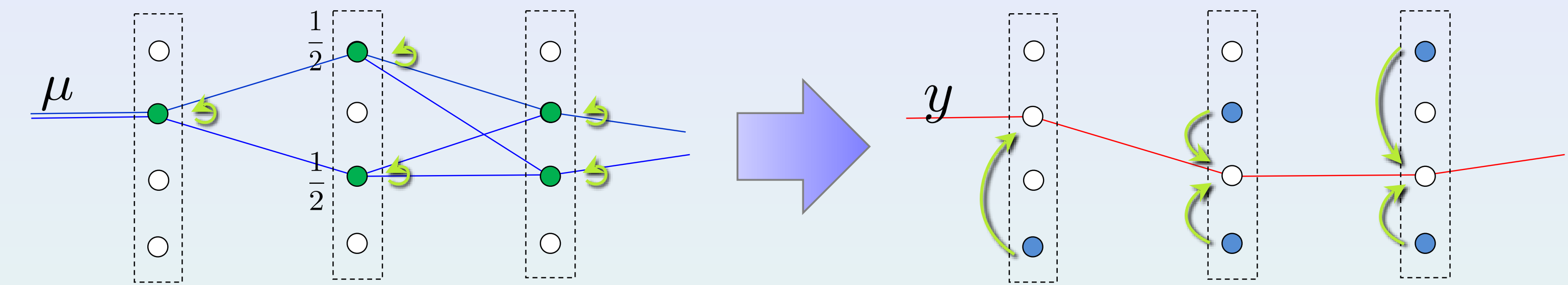
Proposition

Pose "the best partial optimality" as optimization problem. Find the mapping $p: \mathcal{X} \rightarrow \mathcal{X}$ that delivers the maximum problem reduction:

$$\min_{p \in \mathcal{P}} \sum_{u \in \mathcal{V}} |p_u(\mathcal{X}_u)| \text{ s.t. } p \text{ is relaxed-improving; } \mathcal{P} - \text{class of mappings.}$$

Subset-to-one Class of Mappings

Theorem: Let μ be a solution to LP-relaxation: $\mu \in \text{argmin}_{\mu \in \Lambda} \langle f, \mu \rangle$ and $p: \mathcal{X} \rightarrow \mathcal{X}$ be (strictly) relaxed-improving. Then $P\mu = \mu$.



- Fix a *test* labeling y from μ and try substitute other labels with it.
- Mapping p_u selects a subset of labels in u to be substituted with y_u , there are $2^{|\mathcal{X}_u|-1}$ choices.
- Covers all methods marked in the table below

Theorem: Maximum Persistency problem over subset-to-one class of mappings is solvable in polynomial time [13, 14].

- This work: new efficient algorithm, connecting [13] and Pruning-Based-Persistency [16] (CVPR'14).

Generality of Sufficient Conditions

Relaxed-improving condition with natural (local) relaxations are satisfied for all of the following [13, 14]:

multilabel pairwise	Simple DEE [4]	✓	
	MQPBO [8]	✓	
	[11] one-against-all	✓	
	[12] iterative	✓	
pseudo-Boolean higher order	Swoboda et al [16]*	✓	
	Roof dual / QPBO [5]	✓	
	Reductions: HOCR [6], [3]	FLP	
	Bisubmodular relaxations [10]**	BLP	
	Generalized Roof Duality [7]	FLP	
	Persistency by Adams et al [1]	FLP	

– all-to-one class of mappings

BLP = Basic LP Relaxation [20, 19];

FLP = Full Local LP Relaxation, equivalent to [15];

*[16] is higher order but the comparison proof is for pairwise case.

**Result holds for sum of bisubmodular functions over the same hypergraph as the BLP relaxation.

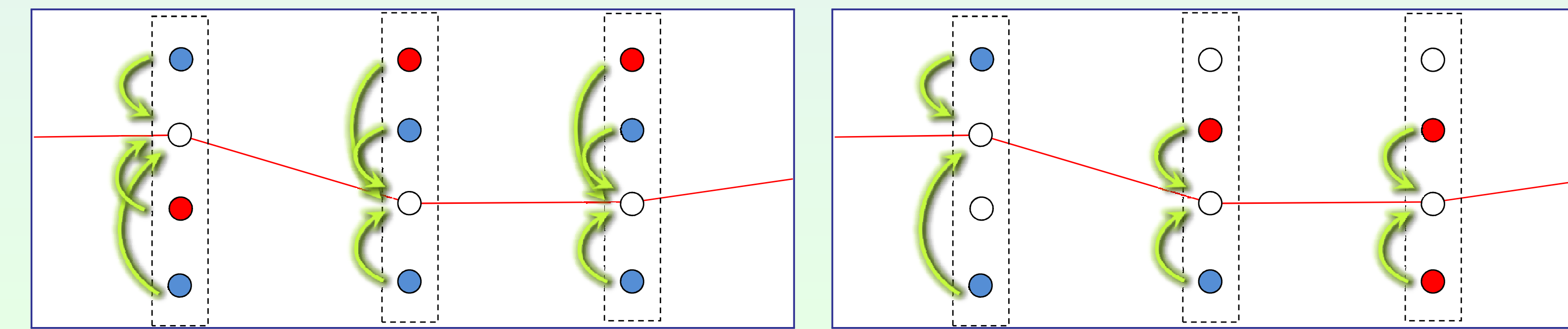
ALGORITHM

Discrete Cutting Plane

- Start with a mapping p that substitutes *everything* with y
- Construct auxiliary 'difference' problem $g = (I - P^T)f$
- Test persistency conditions (relaxed inference for g):

Primal	Dual
$\min_{\varphi, \psi} g, \mu \geq 0 ?$	$\max_{\varphi, \psi} \sum_{u \in \mathcal{V}} \psi_u \geq 0 ?$
$\mu \in \Lambda$	$g_u^\varphi(x_u) \geq \psi_u$
	$g_{uv}^\varphi(x_u, x_v) \geq 0$

- If not satisfied, force p to identity on the following labels x_u :
in the support set of the minimizer: $\mu_u(x_u) > 0$ corresponding to active constraints: $g_u^\varphi(x_u) = \psi_u$



Correctness and Optimality

- Runs in polynomial time;
- Solves the maximum persistency problem exactly when the test relaxation is solved exactly and the solution is a strict relative interior optimal (e.g. interior point method);
- Returns an improving mapping even when the dual is solved sub-optimally – can use fast dual solvers, we used TRW-S [9].

Efficiency

Challenges:

- solving relaxed inference approximately even once is slow
- TRW-S is not finitely converging

How can we iterate such relaxed inference?

Fast implementation with TRW-S

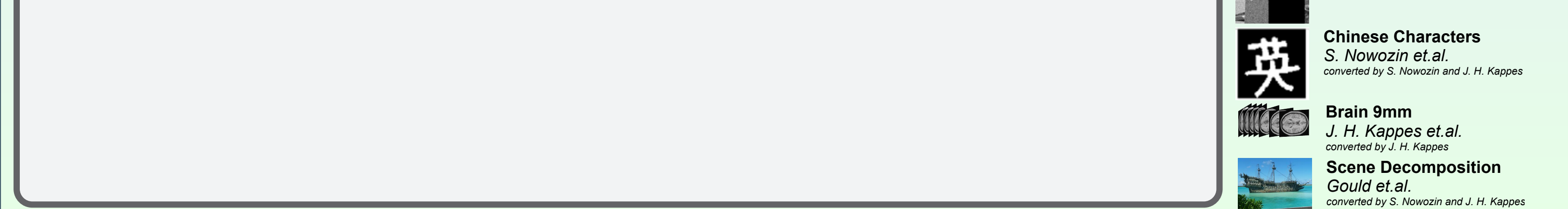
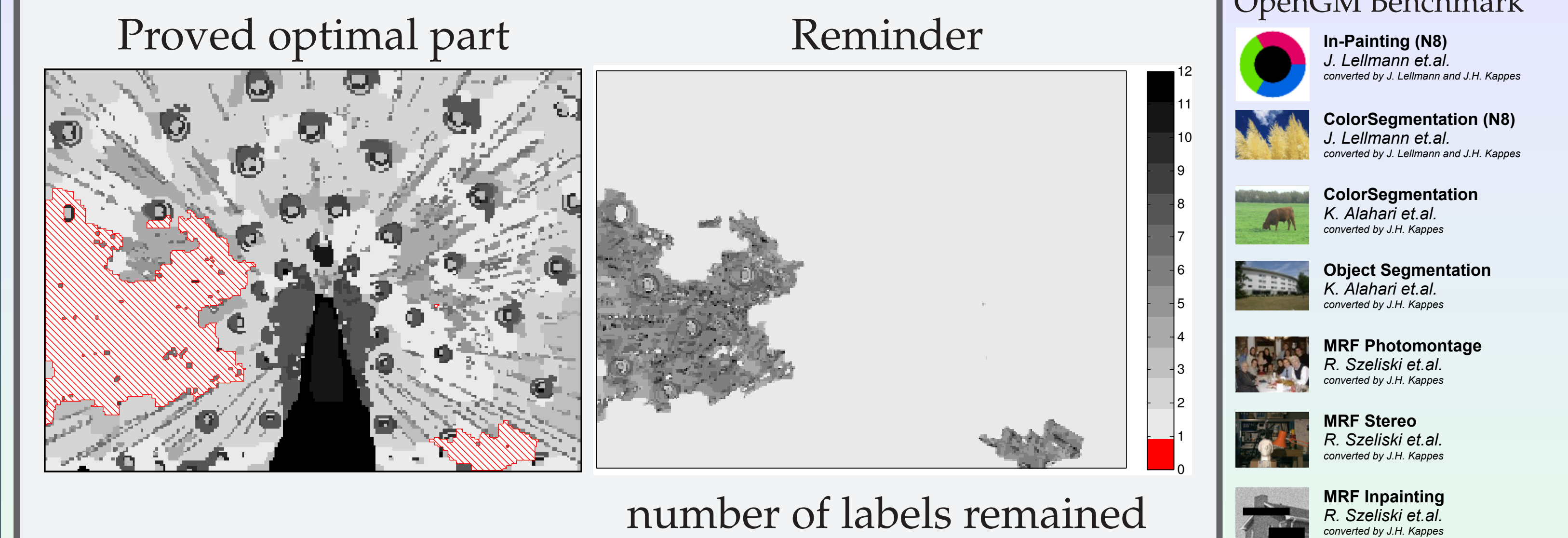
- Warm-start: reuse reparametrizations φ in outer iterations
- Guaranteed to prune something even after 1 iteration of TRW-S
- An optimal **pruning** is often possible before the dual is solved
- Problem **reductions** preserving the sufficient condition
- **Fast message** passing for $(I - P^T)f$ with reductions

Combined Effect of Speedups

Instance	Initialization (1000 it.)	Extra time for persistency				
		no speedups	+reduction	+node pruning	+labeling pruning	+fast msgs
Protein folding 1CKK	8.5s	268s (26.53%)	168s (26.53%)	2.0s (26.53%)	2.0s (26.53%)	2.0s (26.53%)
colorseg-n4 pfau-small	9.3s	439s (88.59%)	230s (93.41%)	85s (93.41%)	76s (93.41%)	19s (93.41%)

EXPERIMENTS

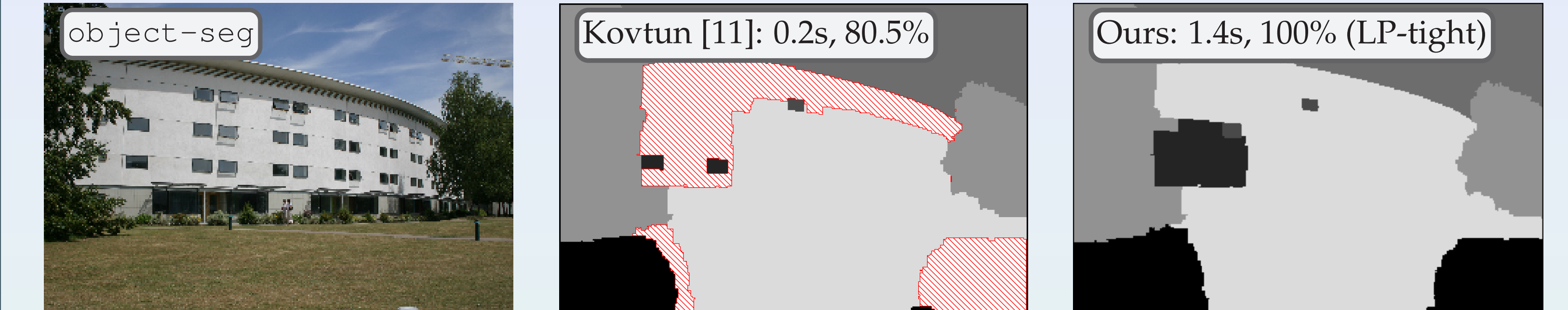
Algorithm Demo



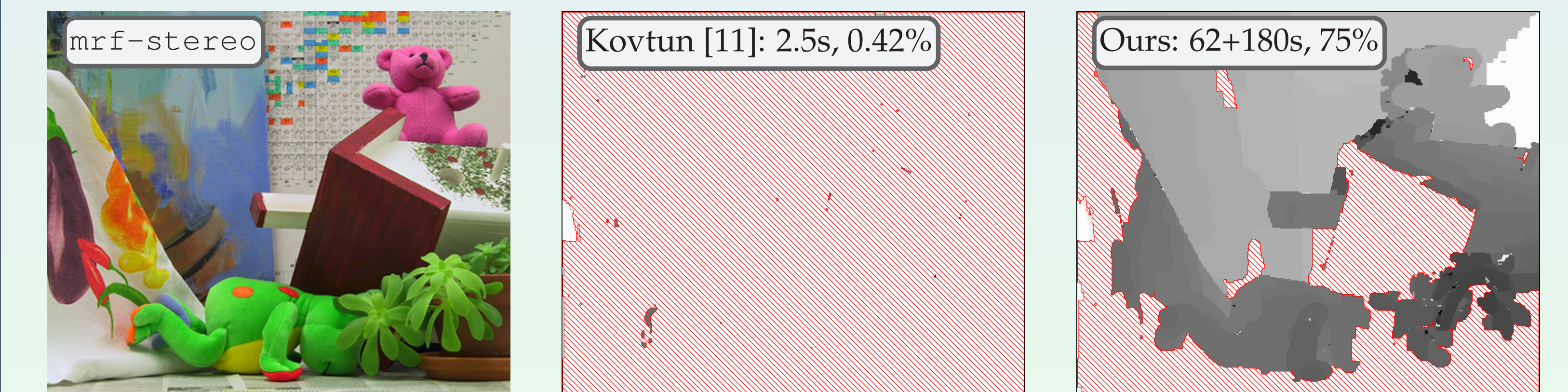
OpenGM Benchmark

Problem family	#I	#L	#V	MQPBO	MQPBO-10	Kovtun	[16]-TRWS	Our-TRWS
mrf-stereo	3	16-60	> 100000	93s	22%	866s	16%	2.5h 13% 117s 73.56%
mrf-photomontage	2	5-7	< 514080	22s	11%	87s	16%	3.7h 16% 483s 41.98%
color-seg	3	3-4	< 424720	22s	8%	398s	14%	0.3s 98% 1.3h >99% 61.8s 99.95%
color-seg-n4	9	3-12	< 86400	22s	8%	398s	14%	0.2s 67% 321s 90% 4.9s 99.26%
ProteinFolding	21	< 483	< 1972	685s	2%	2705s	2%	48s 18% 9.2s 55.70%
object-seg	5	4-8	68160	3.2s	0.01%	0.1s	93.86%	138s 98.19% 2.2s 100%

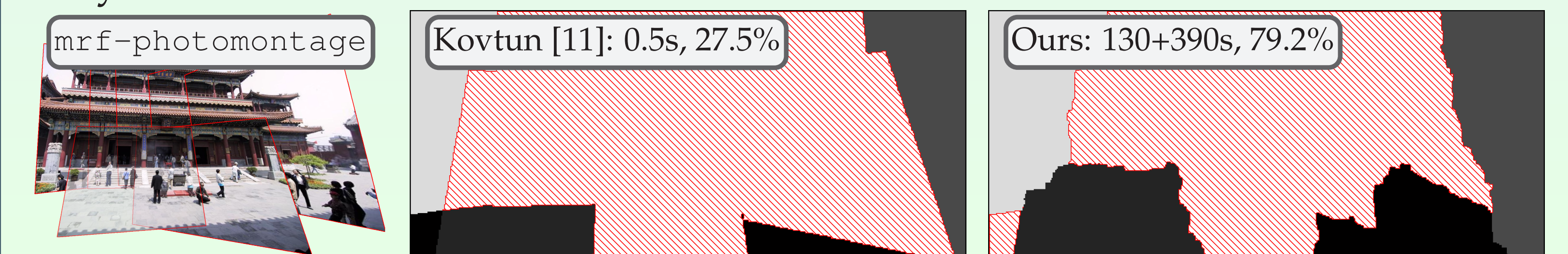
Easy



Hard



Very hard



Implementation

C++/Matlab

<http://icg.tugraz.at/Members/shekhovtsov/persistency>