

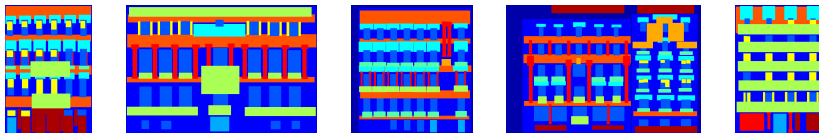
Spatial Pattern Templates for Recognition of Objects with Regular Structure

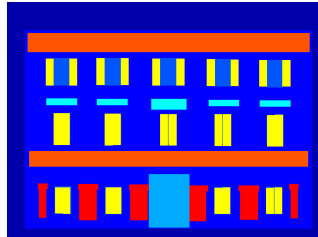
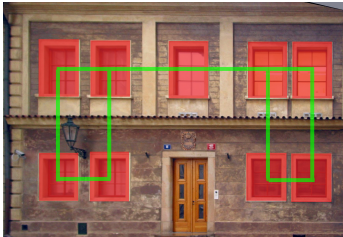
GCPR 2013

Radim Tyleček and Radim Šára

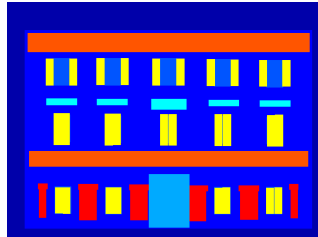
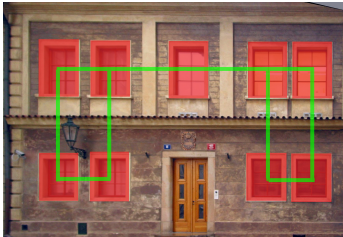


Center for Machine Perception
Czech Technical University in Prague
cmp.felk.cvut.cz

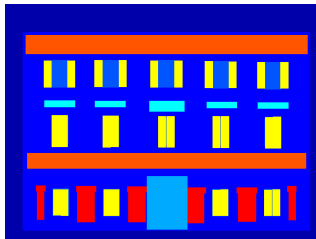
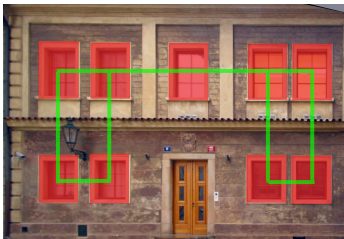




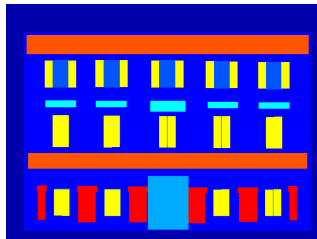
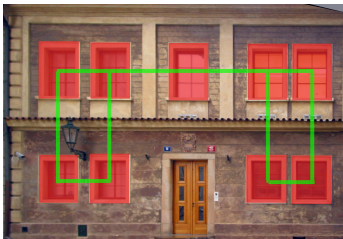
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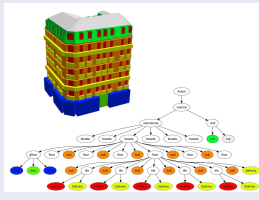


- **Observation:** Some objects in images have regular layout.
- **Regularity:** Repetition of elements according to simple rules (symmetry).
- **Task:** Incorporate regular contextual cues as a structure prior for recognition.
- **Problem:** How to specify a language for complex relations between many object instances of many classes?

Shape Grammars

[Simon 2011]

- set of production rules
- restrictive split layout
- grammar specification

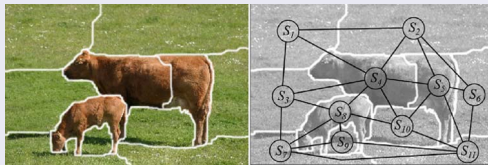


[Simon 2011] Simon, Teboul, Koutsourakis, Paragios: Random exploration of the procedural space. IJCV (2011)

[Gould 2008] Gould et al.: Multi-class segmentation with relative location prior. IJCV (2008)

[Schmidt 2010] Schmidt, Murphy: Convex structure learning: Beyond pairwise potentials. AISTATS (2010)

Sparse Graphical Models [Gould 2008]

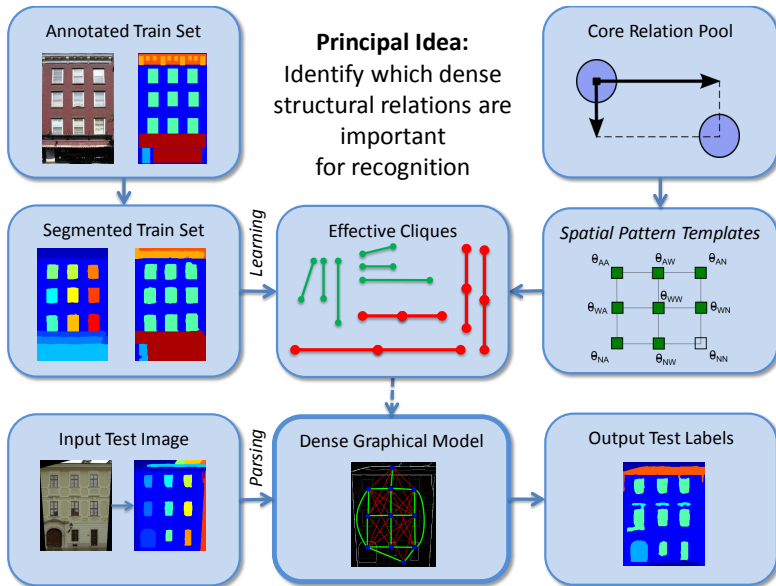


- adjacency, associative potentials
- complex relations not captured

Dense Graphical Models [Schmidt 2010]

- complete, high order cliques
- learning weights jointly in large graphs intractable





Input

X – rectified image data

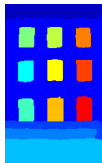
S – unsupervised segmentation

Output

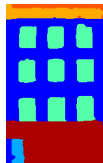
L – class labels for segments in S



X

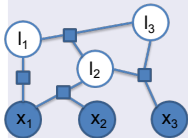


S



L

Probability Model: Conditional Random Field [CRF]



General CRF

find labeling $L : S \rightarrow \mathcal{C}$ that maximizes

$$p(L|X, S) = \frac{1}{Z} \prod_{q \in Q(S)} \exp\left(\sum_{j \in \Phi_q} \theta_j \varphi_j(\mathbf{l}_q, \mathbf{x}_q, \mathbf{s}_q)\right)$$

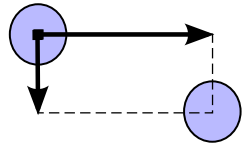
topology given by cliques (factors) in $Q(S)$

[CRF] Lafferty et al.: CRF: Probabilistic models for segmenting and labeling sequence data. ICML (2001)

SPT = representation for learning dense structural relations

1. Specify core attribute relation functions

relations act on attributes of segments tuples



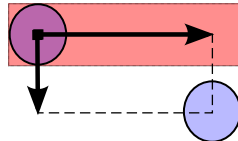
SPT = representation for learning dense structural relations

1. Specify core attribute relation functions

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2. Discretize relation functions

value range is split into discrete intervals



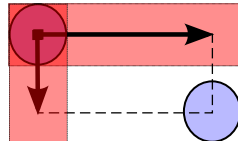
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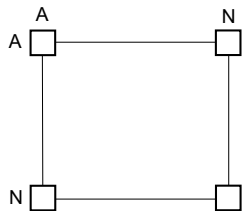
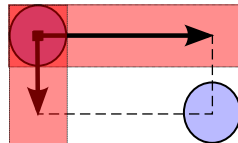
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subsets in Cartesian product of relations



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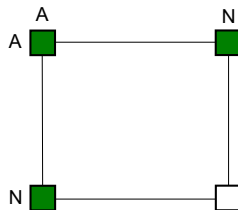
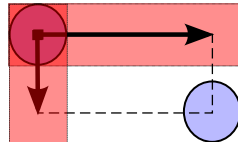
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4. Template domain

indicate allowed combinations



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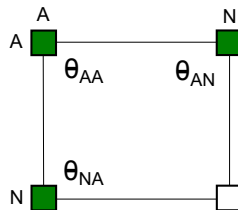
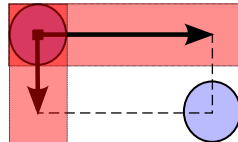
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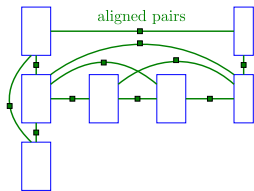
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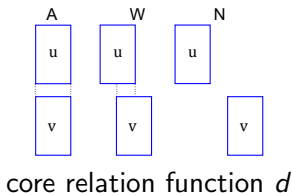
5. Learn weights

for each allowed combination





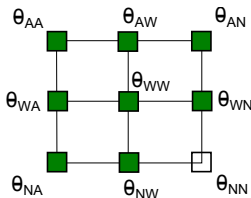
factor graph



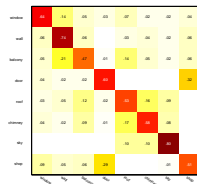
core relation function d

- capture **pair-wise alignment**
- connect two segments aligned horizontally or vertically
- relative position relations d_1, d_2
- nesting, overlap possible
- statistical potential [Tighe11]

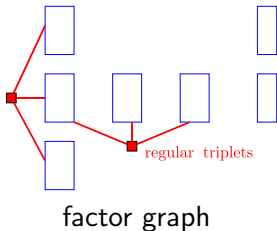
$$\varphi_2(u, v) = \theta_{d_1 d_2} f_c(l_u, l_v, d_1, d_2)$$



SPT domain



label co-occurrence



- capture basis for **repetitive structure** (rows, columns)
- connect three equally spaced segments
- relative position relation
- similarity in segment size
- generalized associative potential

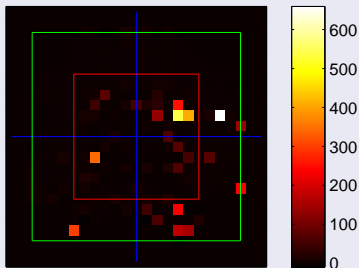
[Kohli 2009]

$$\varphi_3(u, v, w) = \begin{cases} \theta_c & \text{if } l_u = l_v = l_w, \\ \theta_0 & \text{if different,} \\ 0 & \text{if irregular} \end{cases}$$

- enforcing same labels in a triplet

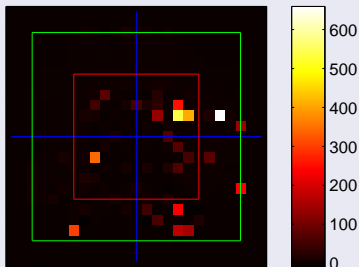
Learning Algorithm

- piece-wise estimation of parameters θ
- unary SVM classifier
- CRF pseudo-likelihood maximization (50 instances)

Aligned Pairs weights $\theta_{d_1 d_2}$

Learning Algorithm

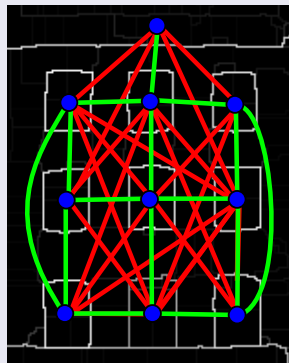
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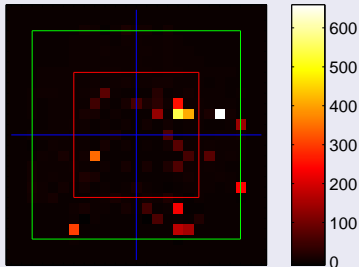
Decoding Algorithm

- recognition of labels L
- max-product tree-reweighted message passing
- voting scheme



Learning Algorithm

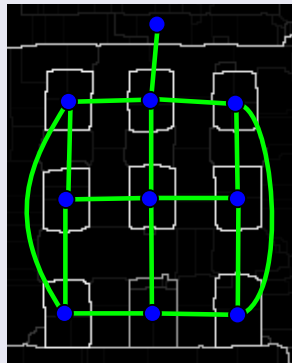
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ECP Monge – 104 images, 8 classes

[3L]: 85.1%, [SG]: 74.7%

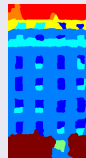
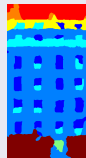
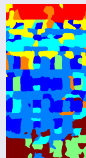
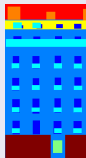


image
accuracy

GT
[%]

NC
59.6

AP
79.0

APRT
84.2

SGT
88.5

[3L] Martinovic et al.: A three-layered approach to facade parsing. ECCV (2012)

[SG] Simon, Teboul, Koutsourakis, Paragios: Random exploration of the procedural space. IJCV (2011)

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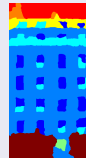
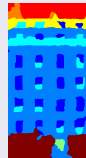
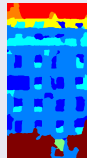
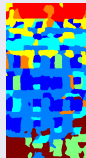
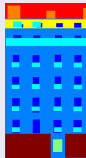


image
accuracy

GT
[%]

NC
59.6

AP
79.0

APRT
84.2

SGT
88.5

eTrims – 60 images, 8 classes

[3L]: 81.9%, [HCRF]: 65.8%



image
accuracy

GT
[%]

NC
56.7

AP
77.4

APRT
82.1

SGT
93.7

[3L] Martinovic et al.: A three-layered approach to facade parsing. ECCV (2012)

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New public dataset, 400 images, rectified, annotated

Website: cmp.felk.cvut.cz/~tylecr1/facade/

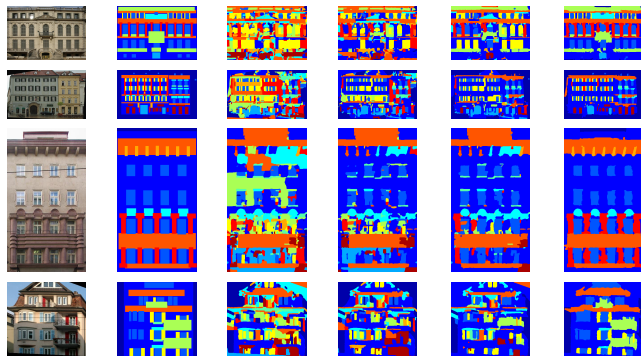


image
acc

GT
[%]

NC
33.2

AP
54.3

APRT
60.3

SGT
84.8

12 classes:

- facade
- molding
- cornice
- pillar
- window
- door
- sill
- blind
- balcony
- shop
- deco

General

Spatial Pattern Template – new representation for learning dense structural relations

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Templates for Regular Scenes

Aligned Pairs – capture pairwise alignment and co-occurrence

Regular Triplets – capture regular spacing in triplets

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Templates for Regular Scenes

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Regular Triplets – capture regular spacing in triplets

Application to Facade Parsing

Standard Datasets – performance comparable to SOA

CMP Facade Database – new 12-class challenge



Center for Machine Perception
Czech Technical University in Prague
cmp.felk.cvut.cz/~tyllec1/facade

