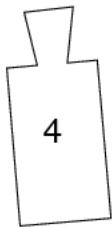
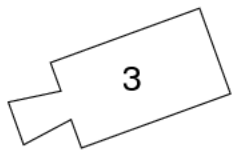
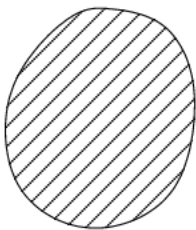
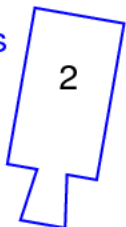
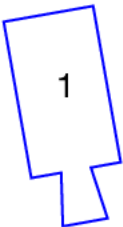
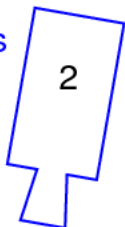
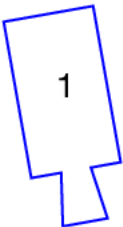


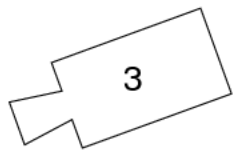
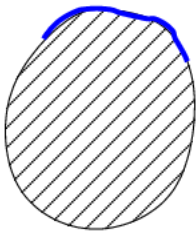
Stereo cams



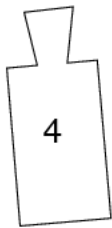
Stereo cams



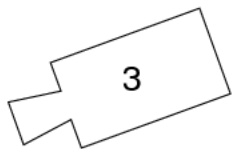
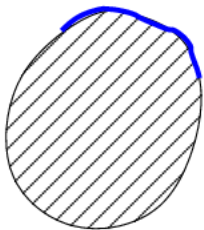
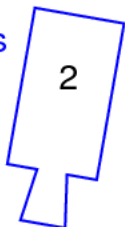
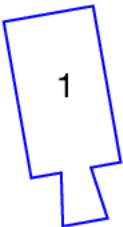
reconstruction 1



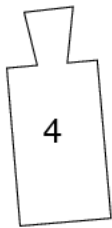
Tracking starts in 1,2



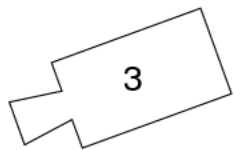
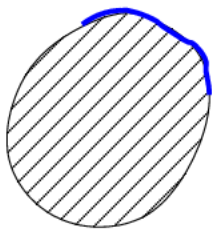
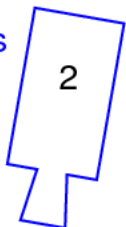
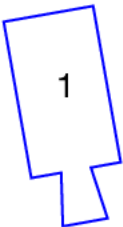
Stereo cams



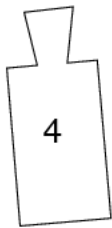
Tracking in 1,2



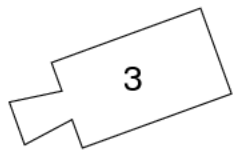
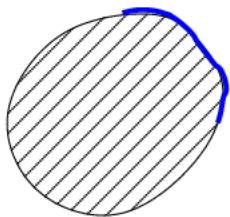
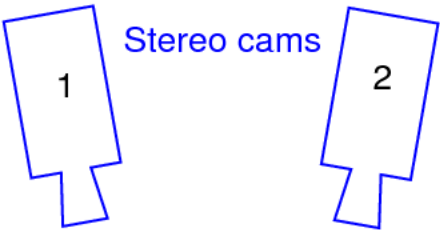
Stereo cams



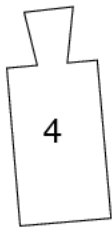
Tracking in 1,2,3



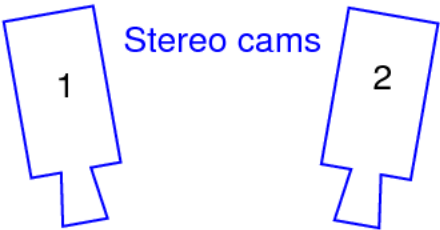
Stereo cams



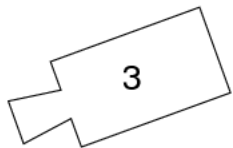
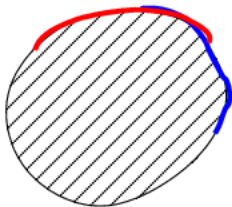
Tracking in 1,2,3



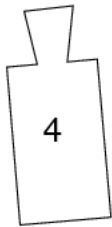
Stereo cams



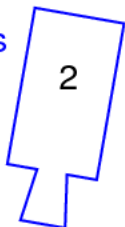
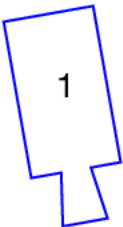
reconstruction 2



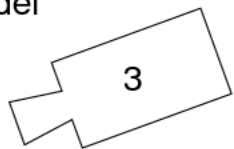
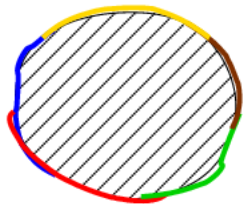
Alignment by tracking



Stereo cams



complete model



Tracking in 1,2,3,4

