

x .. measurements  
y .. labels

For each location, compute probabilities for each label depending on value of x:  $p_x(y)$

REPEAT

    FOR each location

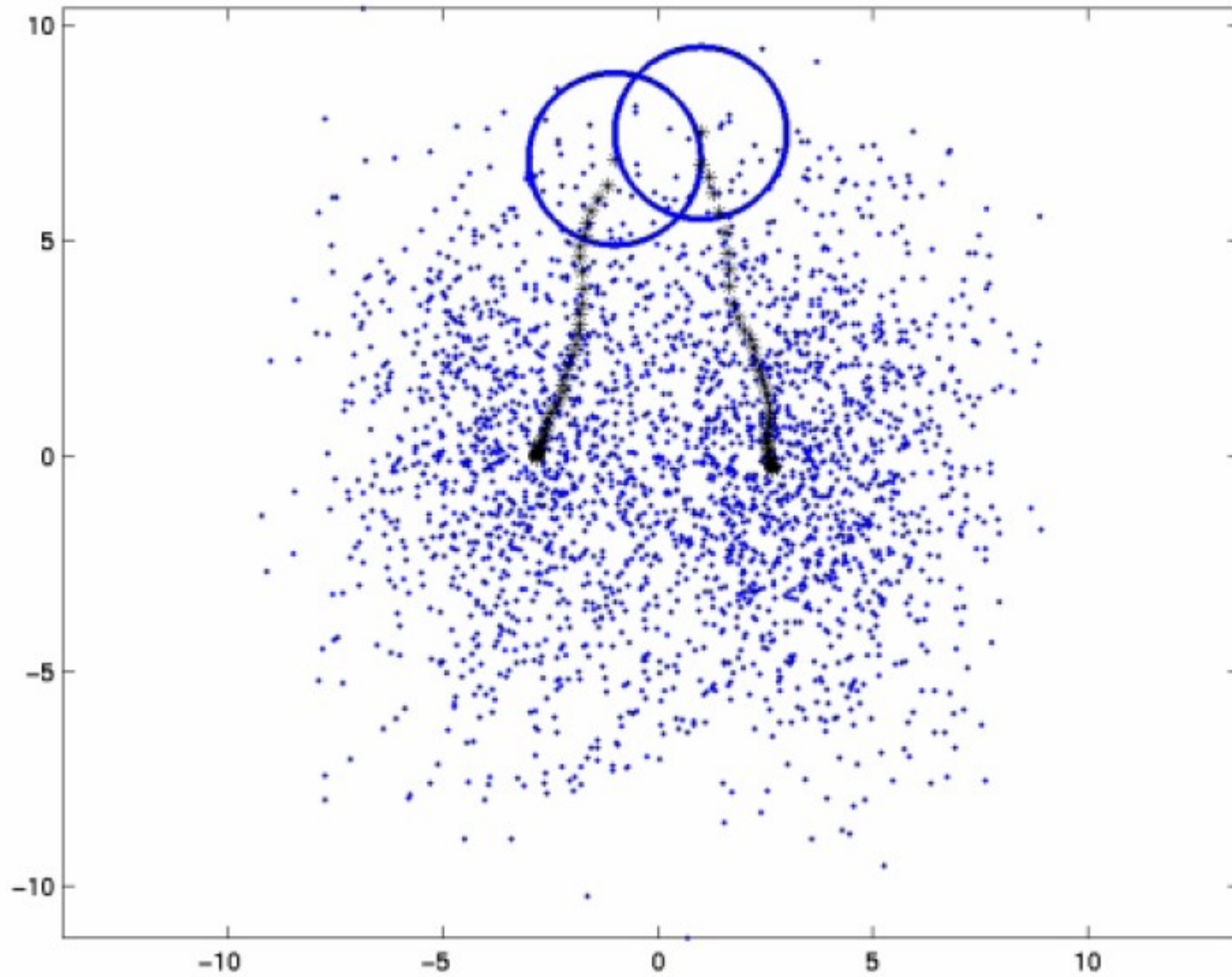
        update probability of labellings  
        based on probabilities in the  
        neighborhood

UNTIL (a maximum of an objective function, F is reached)

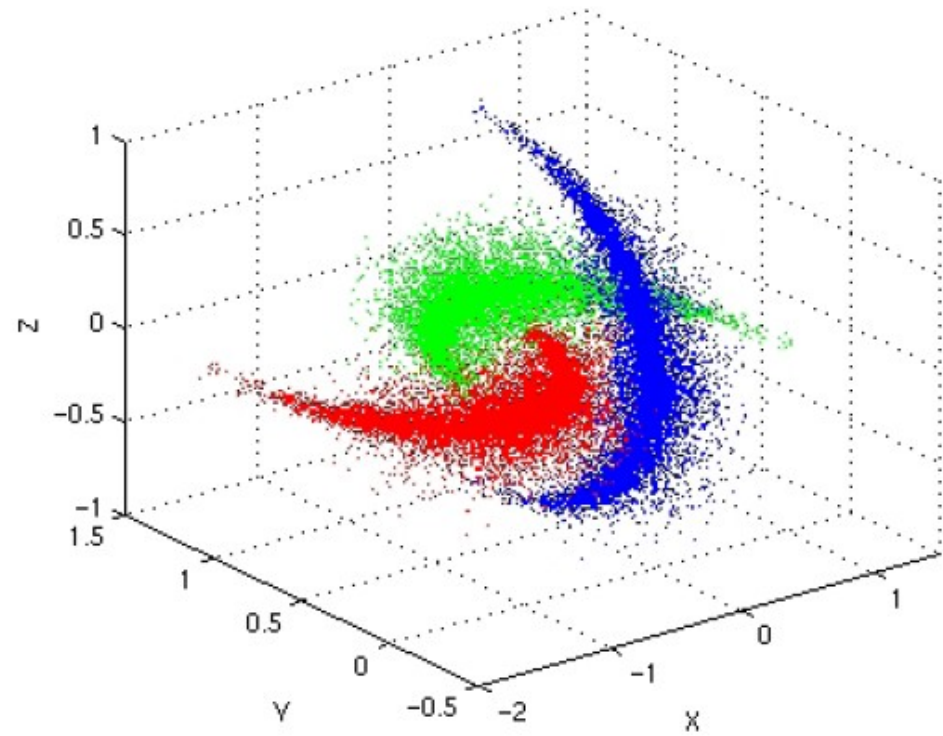
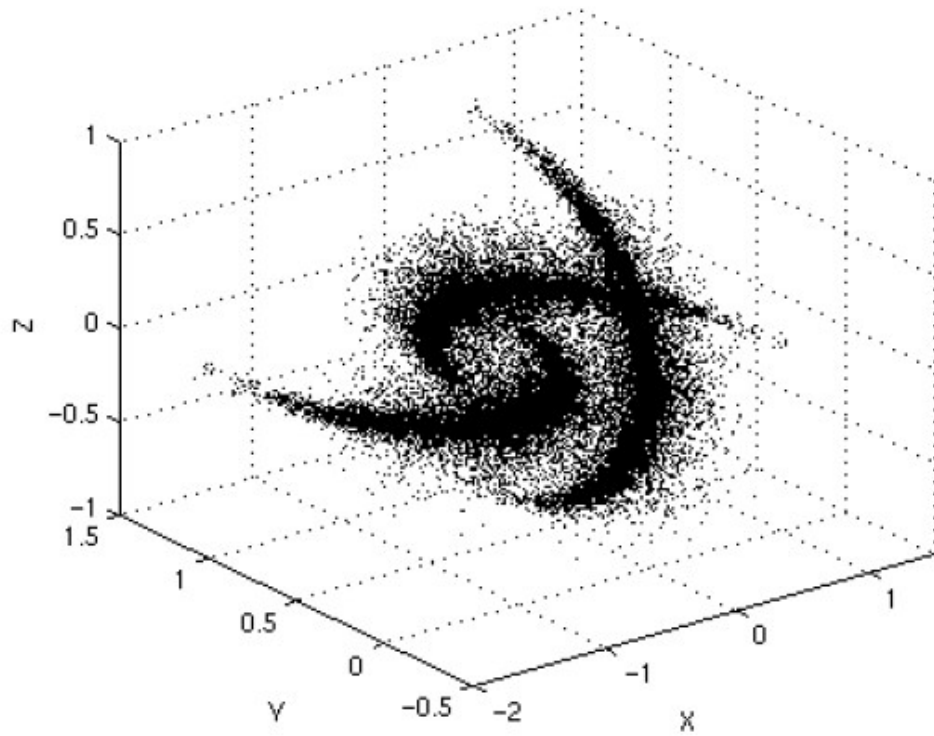
    OR (probabilities cease to change)

Return current solution

# Mean shift - progress



# Mean shift - example



Figures from CVonline: [Mean shift clustering](#)